



# Joint Optimization of Pricing Strategies and Inventory Control with Continuous Stochastic Demand

Yongqiang Wang, Michael C. Fu, and Steven I. Marcus

A. JAMES CLARK  
SCHOOL OF ENGINEERING

## Introduction

- Dynamic pricing and inventory control
  - Demand depends on the price.
  - What amount to order? what price to charge?
  - How to jointly optimize the initial order and the pricing policy?

- Demand model

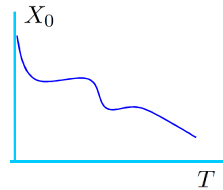
$$D_t = \int_0^t \lambda(p_s) ds + \int_0^t \sigma(D_s, p_s) dB_s$$

- Inventory level  $X_t = X_0 - D_t$

$$dX_t = -dD_t = -\lambda(p_t)dt - \sigma(X_0 - X_t, p_t)dB_t$$

- Maximize the following objective

$$E \left[ \int_0^{\tau \wedge T} p_s dD_s - c(X_s) ds \right]$$



## Simulation-based Method

- Pricing policy

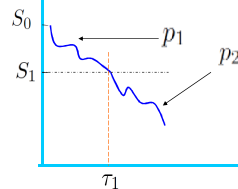
$$S = S_0 > S_1 > \dots > S_{N-1} > S_N = 0$$

$$\tau_k = \inf \{ t \geq 0 : X_t = S_k \}$$

$$\pi_f = \{ S_1, \dots, S_{N-1}, p_1, \dots, p_N \}$$

- Objective

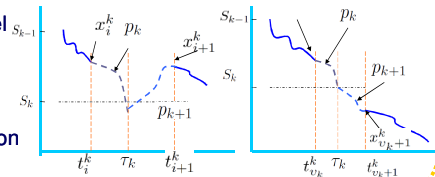
$$\sup_{\pi_f, S} E \left[ \sum_{k=1}^N \int_{\tau_{k-1}}^{\tau_k \wedge T} -p_k dX_s - c(X_s) ds \mid X_0 = S \right]$$



- Simulation of inventory level

- Derive efficient gradient estimators w.r.t decision variables

- Use stochastic approximation to find optimal value

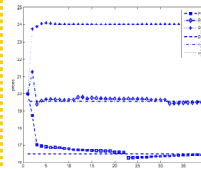


## MAIN RESULTS

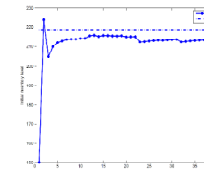
- Developed an efficient simulation algorithm to generate sample paths of inventory level
- Developed an efficient gradient estimator for stopping times based on Brownian bridge
- Derived an unbiased gradient estimator for performance functions with indicator functions
- Proved the convergence of SA with the obtained gradient estimator

Table 1: Infinite Time Sensitivity Estimation Results (Standard Error in Parentheses)

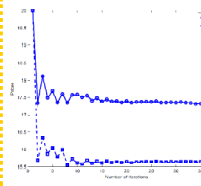
	$\sigma = 1$	$\sigma = 3$	$\sigma = 5$	$\sigma = 7$
$\partial V / \partial p_1$				
LR	5.91(2.55)	4.02(1.27)	4.30(0.78)	5.03(1.24)
PW	5.47(0.18)	5.40(0.32)	5.08(0.40)	3.88(0.50)
ANA	5.52	5.26	4.72	3.92
$\partial V / \partial p_2$				
LR	18.85(2.00)	16.03(0.51)	15.44(0.38)	14.57(0.32)
PW	16.79(0.09)	16.17(0.17)	16.01(0.22)	15.43(0.27)
ANA	16.63	16.367	15.83	15.03
$\partial V / \partial p_3$				
LR	27.75(0.01)	27.47(0.03)	26.97(0.06)	26.12(0.09)
PW	27.73(0.01)	27.47(0.03)	26.99(0.06)	26.36(0.09)
ANA	27.74	27.48	26.94	26.14
$\partial V / \partial S$				
LR	10.28(0.32)	9.85(0.14)	9.88(0.08)	9.83(0.13)
PW	10.05(0.02)	10.03(0.04)	9.98(0.04)	9.86(0.05)
ANA	10.00	9.96	9.88	9.76
$\partial V / \partial c$				
LR	505.3(0.3)	508.2(0.09)	515.3(1.5)	531.1(2.2)
PW	-303.3(0.3)	-309.9(0.09)	-316.0(1.5)	-330.8(2.1)
ANA	-500.5	-504.5	-512.5	-524.5
$\partial V / \partial \sigma$				
LR	0.97(1.66)	-1.75(0.90)	-4.46(0.48)	-5.90(0.48)
PW	-1.51(0.31)	-3.28(0.34)	-4.64(0.39)	-7.38(0.44)
ANA	-1.00	-3.00	-5.00	-7.00



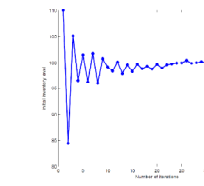
(a) Price



(b) Inventory



(a) Price



(b) Inventory

## CONCLUSIONS

- Developed a simulation-based framework for solving dynamic pricing and inventory control problems with very general demand models
- Unbiasedness of the gradient estimator and theoretical convergence of the algorithm
- Effectiveness demonstrated by numerical results.